AN INJECTIVITY RADIUS ESTIMATE IN TERMS OF METRIC SPHERE

SHICHENG XU

ABSTRACT. In this paper we prove that if a point p in a complete Riemannian manifold is not a cut point of any point whose distance to p is r, then the injectivity radius of p is strictly large than r. As a corollary we give a positive answer to a problem raised by Z. Sun and J. Wan.

This paper is to answer a question asked by Z. Sun and J. Wan in [2]. Let M be a complete noncompact Riemannian manifold, and let i_p denote the injectivity radius at p of M. Let

$$i(p,r) = \min\{i_x : \forall x \in M \text{ s.t. } d(x,p) = r\},\$$

where d(x, p) is the distance between two points x and p. According to [2], they defined a number $\alpha(M)$ to be

$$\alpha(M) = \liminf_{r \to \infty} \frac{i(p, r)}{r},$$

which is called the *injectivity radius growth* of M. Because in the definition of $\alpha(M)$ r goes to infinity and the distance from p to any other fixed point is a definite finite number, it can be seen directly (see also a proof in [2]) that $\alpha(M)$ is not depending on p. One of their questions in [2] is the following

Question 1 ([2]). For a complete noncompact manifold M, can one prove that every geodesic $\gamma: (-\infty, +\infty) \to M$ is a line as long as $\alpha(M) > 1$?

In other words, they asked that whether the injectivity radius of every point in M is infinity when $\alpha(M) > 1$? A positive answer of Question 1 directly follows from Proposition 2 below.

Proposition 2. Let M be a complete Riemannian manifold and $p \in M$. If for some r > 0, p is not a cut point of any point x such that d(x, p) = r, then the injectivity radius i_p at p > r.

Remark 3. The point in proving Proposition 2 is to show that the minimal geodesics for p to points in the metric sphere $S_r(p) = \{x \in M : d(p, x) = r\}$ covers the whole ball $B_r(p) = \{x \in M : d(p, x) \leq r\}$. Though the conclusion

Date: February 2, 2015.

²⁰⁰⁰ Mathematics Subject Classification. 53C20. 53C35.

Project 11171143 supported by NSFC.

Keywords: Injectivity radius, Complete manifold.

of Proposition 2 may be already known by some experts, it seems that it is still not well-known and there is no proof can be found in the earlier literature. That is the reason why I decided to write down a proof.

Remark 4. It can be proved that for $p \in M$ and r > 0, if the minimizing geodesic from p to each point x such that d(x,p) = r is unique, then the injectivity radius of $p \ge r$. However, the proof is more complicate than that of Proposition 2. So we will not go into that case here.

Proof of Proposition 2. Let T_p^1M denote the set of all unit vectors at p in M. Let us denote

$$A(p,r) = \{X \in T_p^1 M : \exp_p(tX) \text{ is minimal on } [0,r') \text{ for some } r' > r\}.$$

It suffices to show that A(p,r) is open and close in T_p^1M . Firstly, it is well-known that the function $\sigma: T_p^1M \to \mathbb{R}^+$,

$$\sigma(X) = \sup\{t : \exp tX \text{ is minimal on } [0, t]\},\$$

is continuous (see 2.1.5 Lemma in [1]). Hence by definition A(p,r) is open. Now let us show that A(p,r) is closed in T_p^1M . Assume a sequence of unit vectors $X_i \in A(p,r)$ converges to a unit vector $X \in T_p^1M$, then the geodesic $\exp(tX_i)$ converges to $\exp(tX)$ point-wisely. Because all geodesic $\exp(tX_i)$ is minimal on [0,r], the limit $\exp(tX)$ is also a minimal geodesic on [0,r], and thus $d(\exp(rX),p)=r$. Moreover, by the assumption of Proposition 2, $\exp(rX)$ is not a cut point of p. Hence, there is $\epsilon>0$ such that $\exp(tX)$ is also minimal on $[0,r+\epsilon]$. Thus $X \in A(p,r)$ and A(p,r) is closed.

Because A(p,r) is open and closed, it coincides with T_p^1M . Therefore the injectivity radius at p is > r.

The following corollaries directly follows from Proposition 2. Recall that p is called a pole if the injectivity radius of p is infinity. In particular, M is diffeomorphic to \mathbb{R}^n by the exponential map $\exp_p: T_pM \to M$ at a pole.

Corollary 5. Let M be a complete non-compact manifold. M possesses a pole at p if (and only if) there is a sequence $r_k \to \infty$ such that p is not a cut point of any point in $S(p, r_k)$.

Corollary 6.

$$\limsup_{r \to \infty} \frac{i(p, r)}{r} > 1,$$

implies that every point in M is a pole. Hence either $\limsup_{r\to\infty}\frac{i(p,r)}{r}\in [0,1]$, or $\limsup_{r\to\infty}\frac{i(p,r)}{r}=\infty$.

Because $\alpha(M) \leq \limsup_{r \to \infty} \frac{i(p,r)}{r}$, Corollary 6 not only answers Question 1, but also strength the homeomorphism result of Theorem 1.2 in [2] to diffeomorphism in the case of dimension 4.

ACKNOWLEDGEMENT

The author thanks Zhongyang Sun for the discussion to bring the author's attention to the problem, and also thanks Jianming Wan for his interest that gave the author motivation to complete this note.

References

- [1] W. Klingenberg. *Riemannian Geometry*. De Gruyter studies in mathematics. Walter de Gruyter, Berlin, 1982.
- [2] Z. Sun and J. Wan. On the injectivity radius growth of complete noncompact riemannian manifolds. *Asian J. Math.*, 18(3):419–426, 2014.

 $E ext{-}mail\ address: shichengxu@gmail.com}$

SCHOOL OF MATHEMATICAL SCIENCES, CAPITAL NORMAL UNIVERSITY, BEIJING, CHINA